

ESE 415: Optimization

Ulugbek S. Kamilov
Computational Imaging Group
Washington University, St. Louis, USA

Today we will talk about

- **Motivating example**
Optimization as a pillar of modern imaging
- **Introduction**
Overview of optimization
- **Class structure**
Assignments, grades, TAs, etc.

Today we will talk about

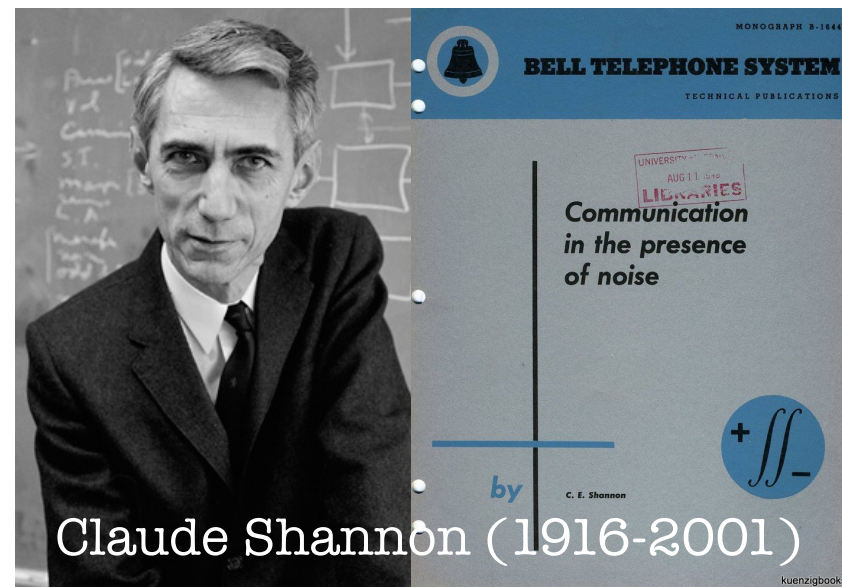
- **Motivating example**
Optimization as a pillar of modern imaging
- Introduction
Overview of optimization
- Class structure
Assignments, grades, TAs, etc.

**Nyquist–Shannon theorem is the bridge
between analog and digital technology**

Nyquist–Shannon theorem is the bridge between analog and digital technology

In 1949, Shannon set the foundation of digital era

Theorem [Shannon]: If a function $f(x)$ contains no frequencies higher than ω_{\max} (in radians per second), it is completely determined by giving its ordinates at a series of points spaced $T = \pi/\omega_{\max}$ seconds apart.

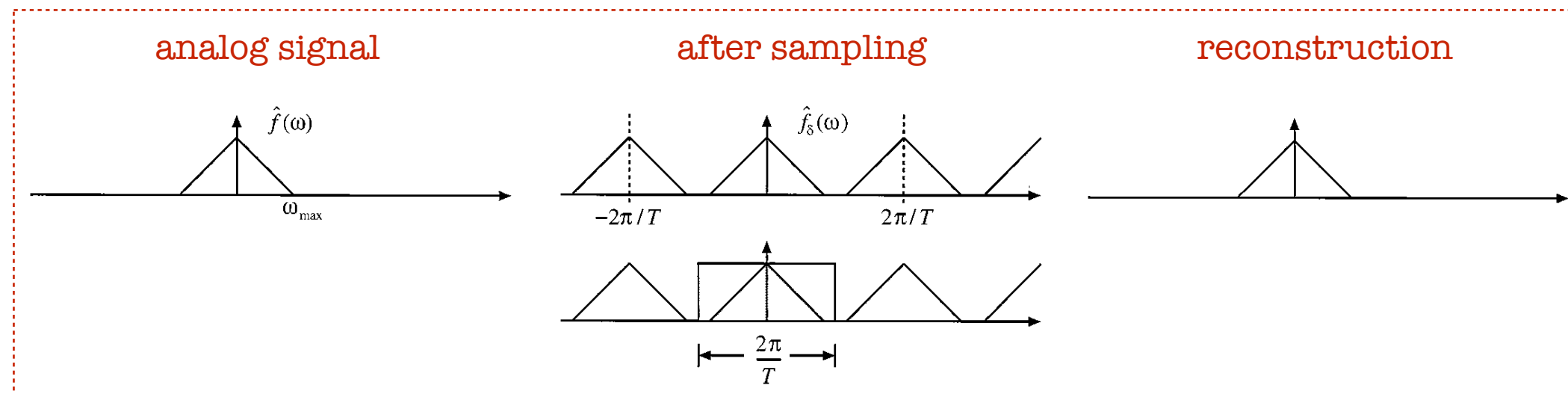


Nyquist–Shannon theorem is the bridge between analog and digital technology

In 1949, Shannon set the foundation of digital era

Theorem [Shannon]: If a function $f(x)$ contains no frequencies higher than ω_{\max} (in radians per second), it is completely determined by giving its ordinates at a series of points spaced $T = \pi/\omega_{\max}$ seconds apart.

Visual representation in Fourier domain

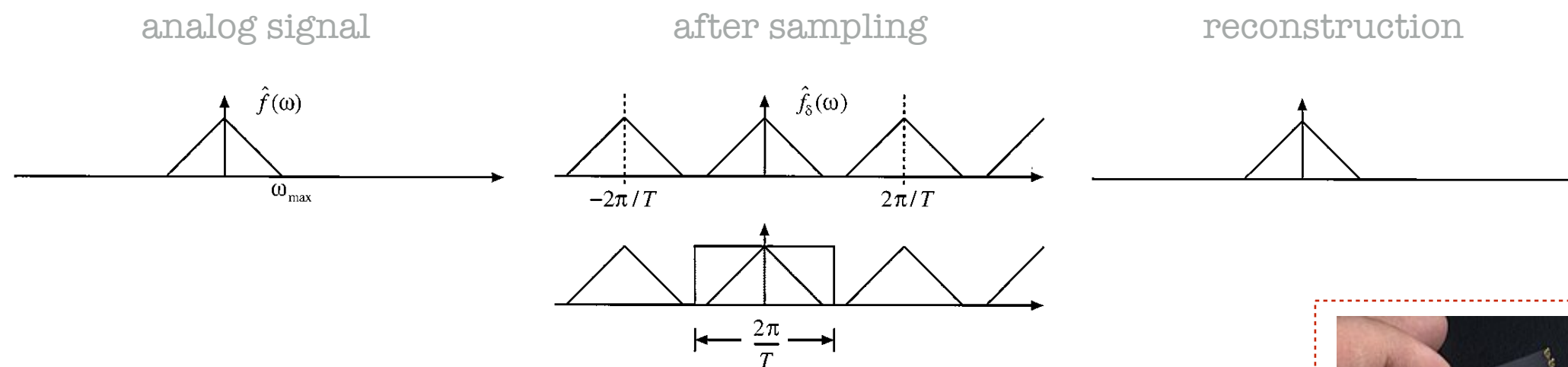


Nyquist–Shannon theorem is the bridge between analog and digital technology

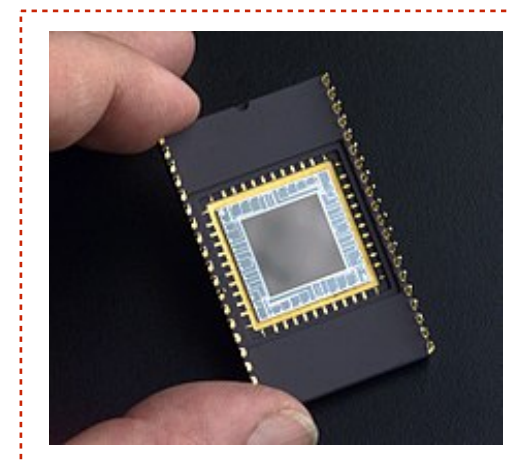
In 1949, Shannon set the foundation of digital era

Theorem [Shannon]: If a function $f(x)$ contains no frequencies higher than ω_{\max} (in radians per second), it is completely determined by giving its ordinates at a series of points spaced $T = \pi/\omega_{\max}$ seconds apart.

Visual representation in Fourier domain



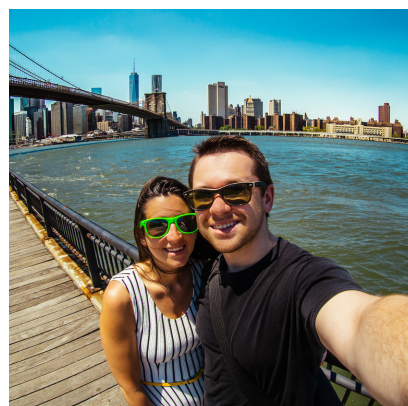
Sampling dictates the way we design sensing systems



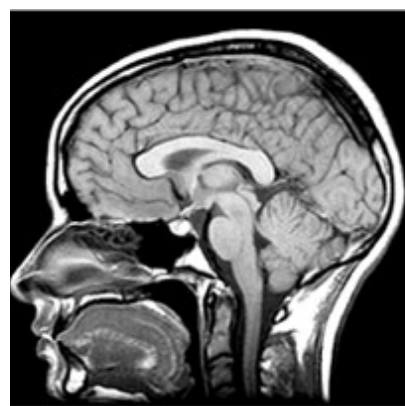
**We are building sensors that acquire
massive quantities of imaging data**

We are building sensors that acquire massive quantities of imaging data

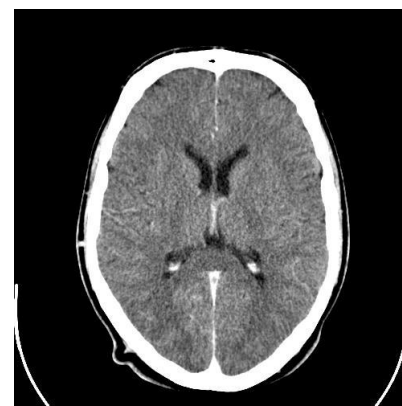
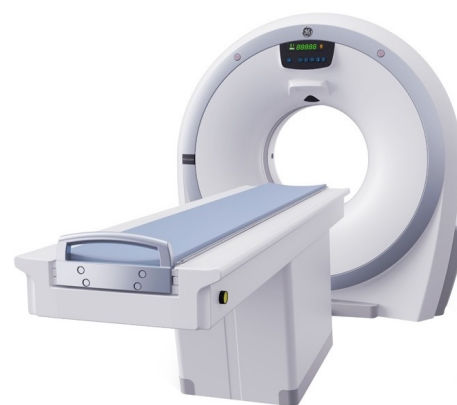
iPhone



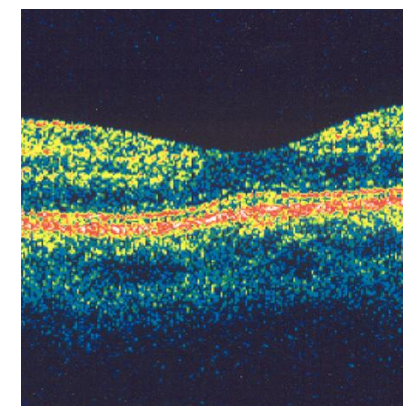
MRI



CT

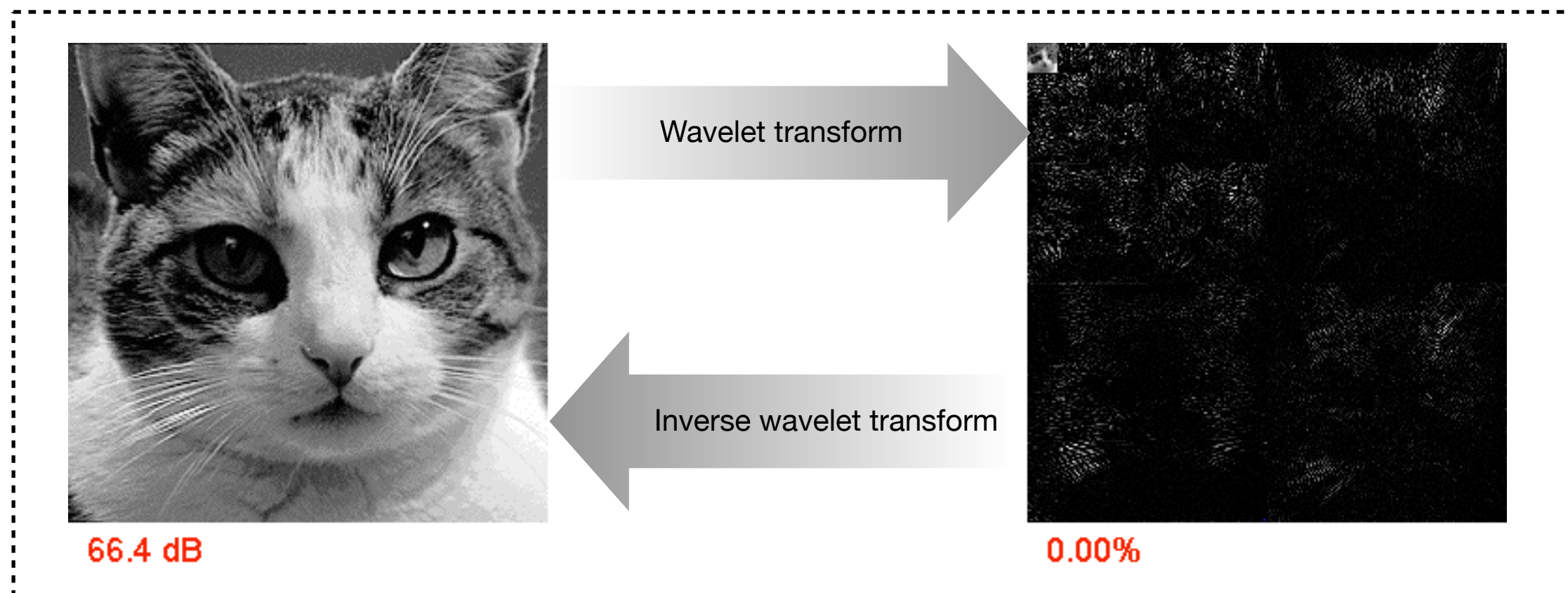


OCT



We also know that visual data is highly redundant

We also know that visual data is highly redundant

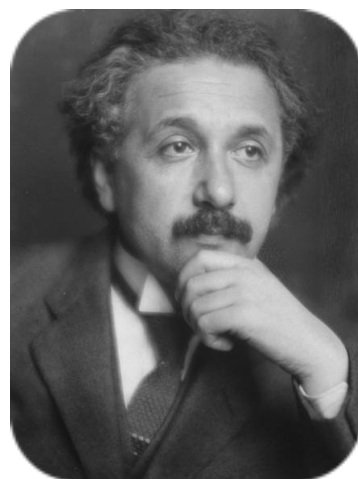
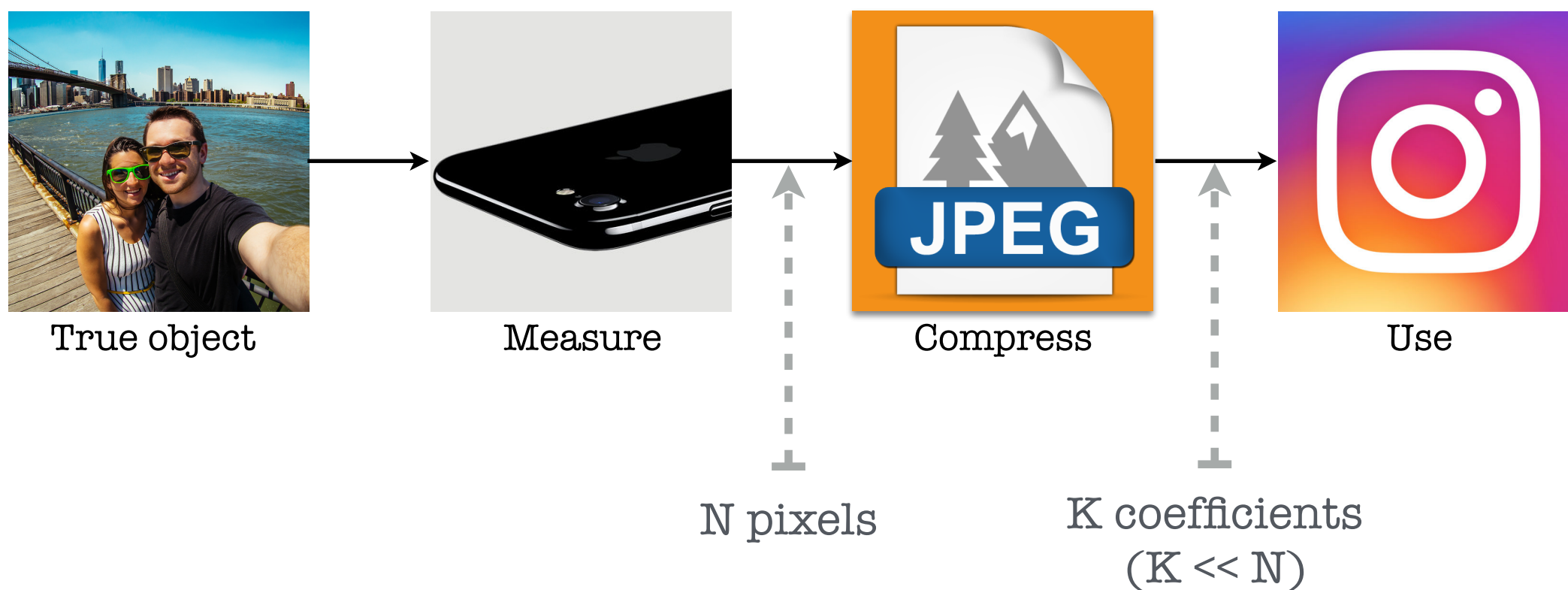


No significant visual quality loss after discarding 90% of coefficients

**Contemporary imaging paradox:
we collect a lot of redundant data**

Contemporary imaging paradox: we collect a lot of redundant data

A long established sensing pipeline in imaging



Is there a smarter way?

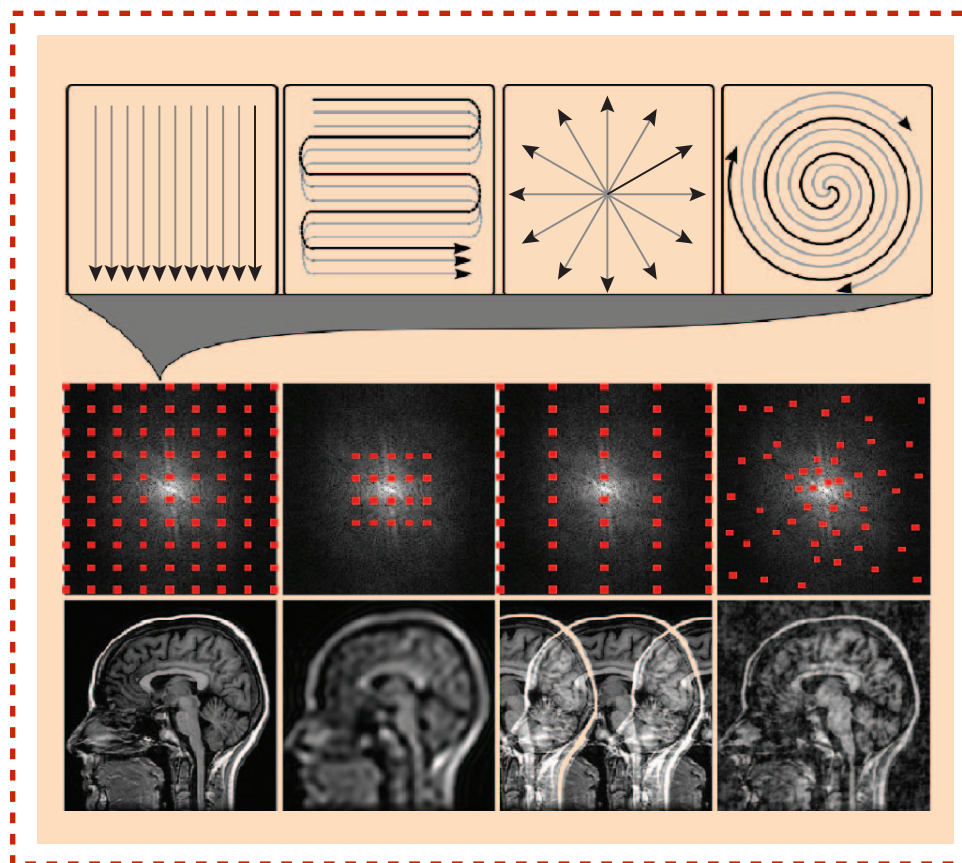
Compressive imaging makes us rethink the design of traditional imaging pipelines

Compressive imaging makes us rethink the design of traditional imaging pipelines

**Acquire compressive measurements
with less samples than Shannon**

Compressive imaging makes us rethink the design of traditional imaging pipelines

Acquire compressive measurements with less samples than Shannon



With traditional reconstruction dropping samples would result in visible artifacts in the image

Compressive imaging makes us rethink the design of traditional imaging pipelines

Acquire compressive measurements
with less samples than Shannon

Formulate reconstruction as a
nonlinear optimization problem

Compressive imaging makes us rethink the design of traditional imaging pipelines

Acquire compressive measurements
with less samples than Shannon

Formulate reconstruction as a
nonlinear optimization problem

$$\min_{\mathbf{f}} \{ \|\mathbf{y} - \mathbf{H}\mathbf{f}\|_{\ell_2}^2 \} \quad \text{s.t.} \quad \|\mathbf{W}\mathbf{f}\|_{\ell_0} \leq K$$

Compressive imaging makes us rethink the design of traditional imaging pipelines

Acquire compressive measurements with less samples than Shannon

Formulate reconstruction as a nonlinear optimization problem

$$\min_{\mathbf{f}} \{ \|\mathbf{y} - \mathbf{H}\mathbf{f}\|_{\ell_2}^2 \} \quad \text{s.t.} \quad \|\mathbf{W}\mathbf{f}\|_{\ell_0} \leq K$$

Code the optimization algorithm and solve on a computer

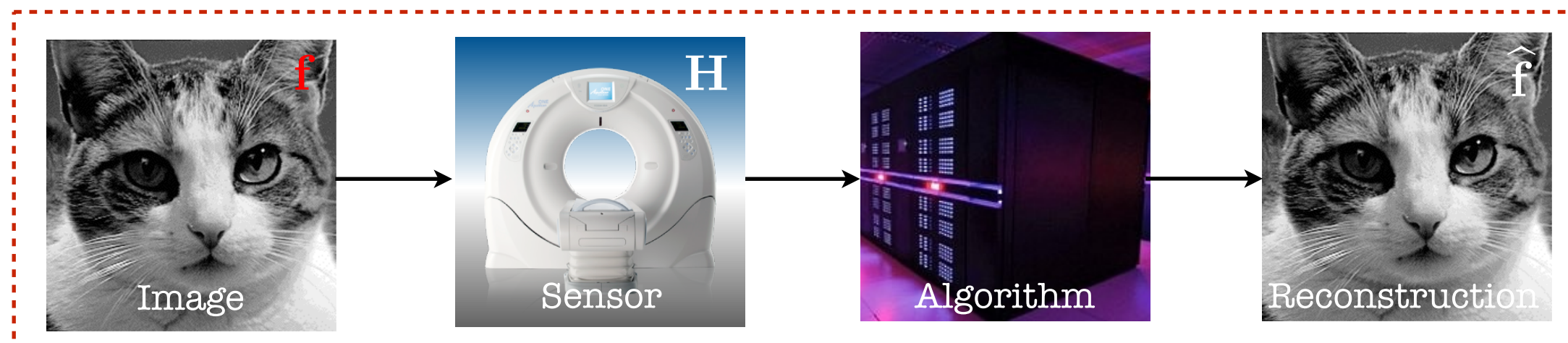
Compressive imaging makes us rethink the design of traditional imaging pipelines

Acquire compressive measurements with less samples than Shannon

Formulate reconstruction as a nonlinear optimization problem

$$\min_{\mathbf{f}} \{ \|\mathbf{y} - \mathbf{H}\mathbf{f}\|_{\ell_2}^2 \} \quad \text{s.t.} \quad \|\mathbf{W}\mathbf{f}\|_{\ell_0} \leq K$$

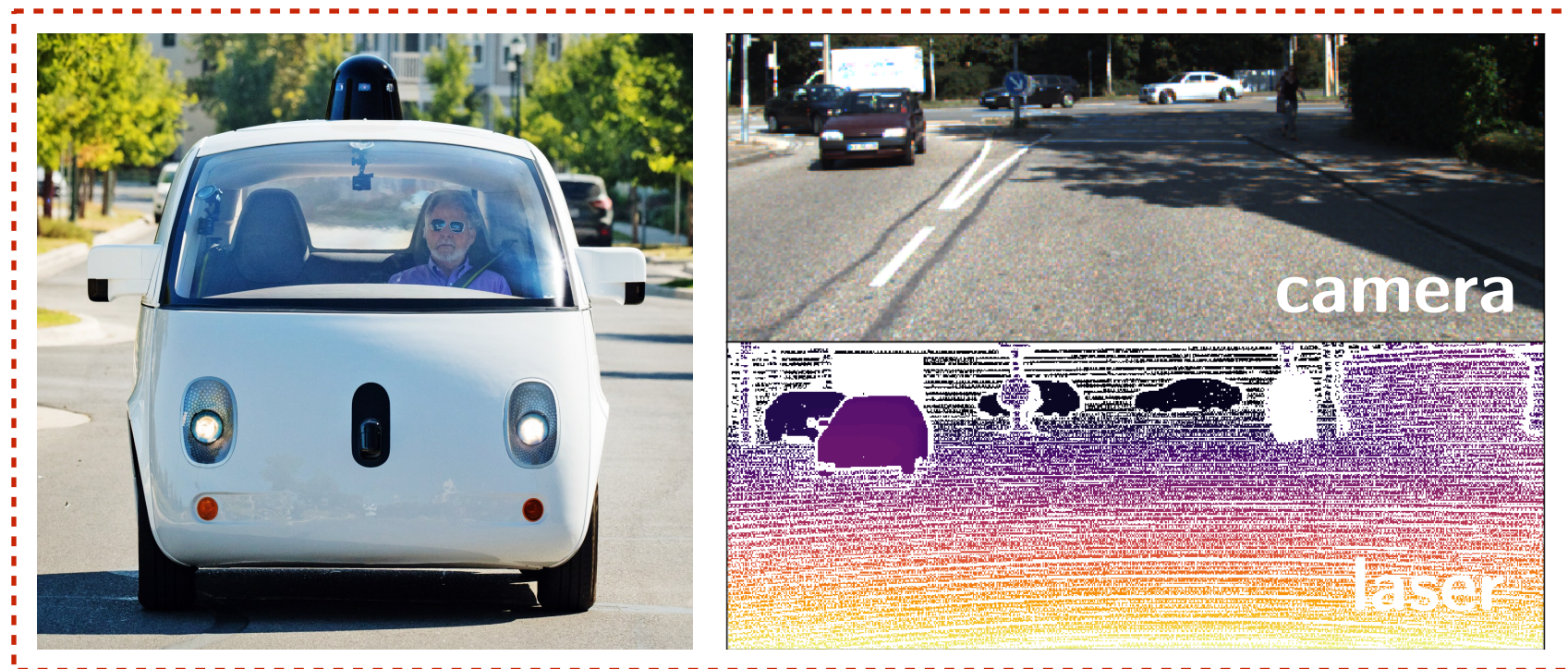
Code the optimization algorithm and solve on a computer



Optimization for improving the resolution of a laser sensor

Optimization for improving the resolution of a laser sensor

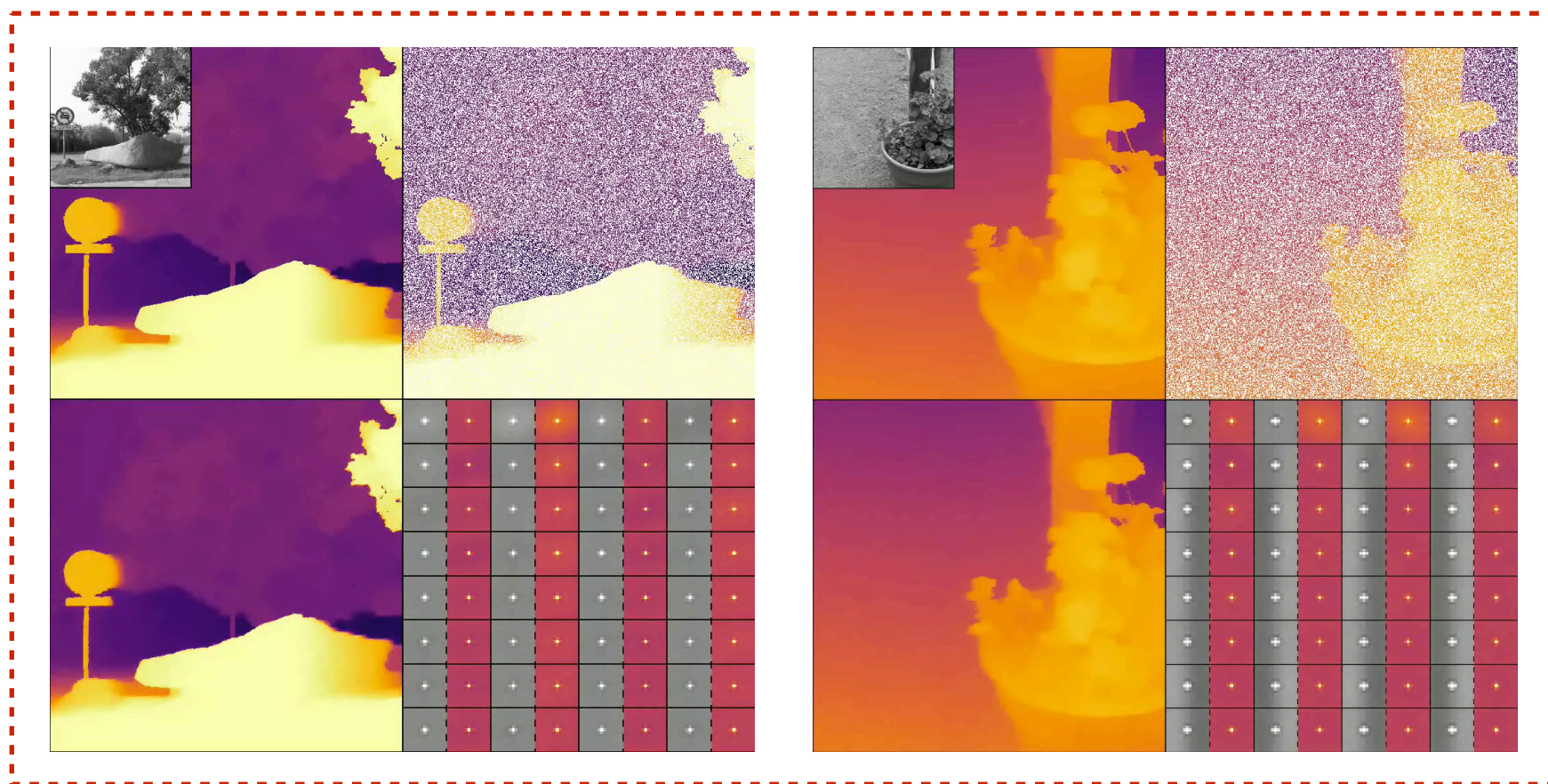
Laser sensors have low-spatial resolution



Optimization for improving the resolution of a laser sensor

Laser sensors have low-spatial resolution

One can use write an optimization problem to enhance the resolution by fusing camera and laser



Today we will talk about

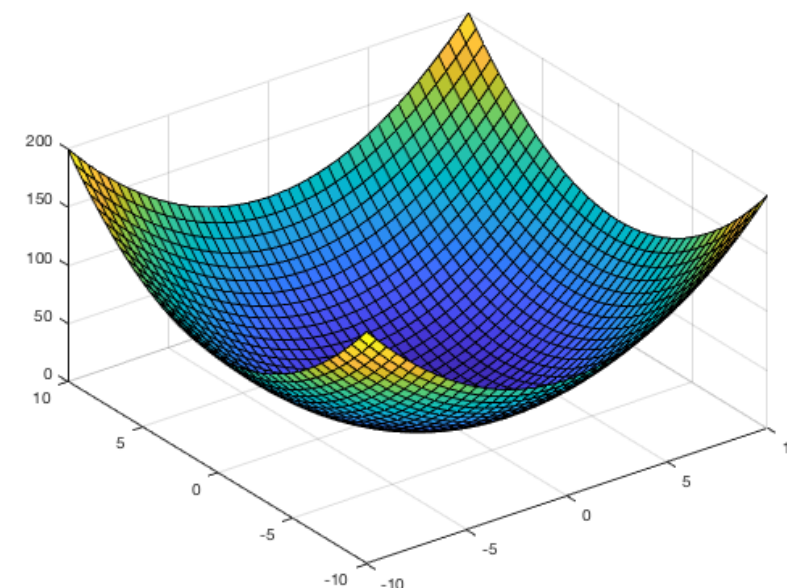
- Motivating example
Optimization as a pillar of modern imaging
- **Introduction**
Overview of optimization
- Class structure
Assignments, grades, TAs, etc.

The goal of optimization is to find the smallest value of a function under constraints

Mathematical optimization problem

$$\begin{array}{ll} \text{minimize} & f(\mathbf{x}) \\ \text{subject to} & \mathbf{x} \in \mathcal{X} \end{array}$$

- Optimization variable: $\mathbf{x} = (x_1, \dots, x_n)$
- Objective function: $f : \mathbb{R}^n \rightarrow \mathbb{R}$
- Constraint set: $\mathcal{X} = \{\mathbf{x} \mid \mathbf{h}(\mathbf{x}) = 0\} \cap \{\mathbf{x} \mid \mathbf{g}(\mathbf{x}) \leq 0\}$
- Optimal solution \mathbf{x}^* has smallest value of f among all vectors that satisfy the constraints



Sample applications of optimization: finance, engineering, and computer science

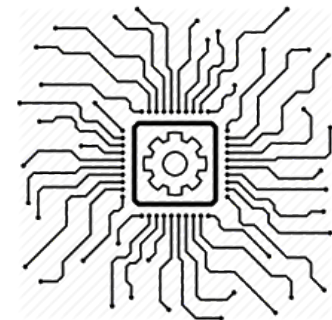
portfolio optimization

- variables: amounts invested in different assets
- constraints: budget, minimum return
- objective: overall risk or return variance



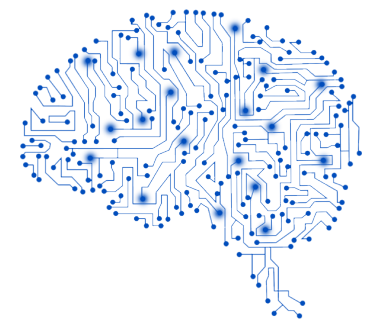
device sizing in electronic circuits

- variables: device width and lengths
- constraints: manufacturing limits, timing requirements
- objective: power consumption



machine learning

- variables: model parameters
- constraints: prior information, parameter limits
- objective: prediction error



Brief history of optimization

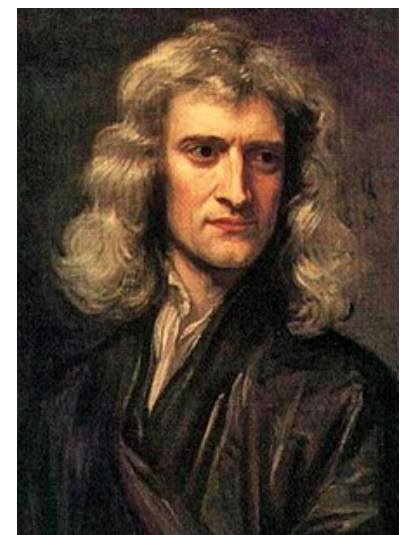
Antiquity: Greek mathematicians solve some optimization problems that are related to their geometrical studies

- Euclid (300bc): minimal distance between a point and a line
- Heron (100 bc): light travels between two points through the path with shortest length when reflecting from a mirror



17th-18th: before the invention of calculus of variations only some separate optimization problems are being investigated

- Kepler (1615): Optimal dimensions of wine barrel. Formulated the secretary problem when searching for a new wife
- Fermat: derivative of a function vanishes at the extreme point the (1636). Shows that light travels between two points in minimal time (1657)



Newton (1660s) and Leibniz (1670s) create mathematical analysis that forms the basis of calculus of variations

Brief history of optimization

19th century: the first optimization algorithms are presented

- Legendre (1806): least square method, which also Gauss claims to have invented
- Cauchy (1847): presents the gradient method
- Gibbs shows that chemical equilibrium is an energy minimum



20th century: the field of algorithmic research expands as electronic calculation develops

- von Neuman and Morgenstern (1944): dynamic programming for solving sequential decision problems
- Dantzig (1947): simplex method for solving LP-problems
- Kuhn and Tucker (1951): reinvent optimality conditions for nonlinear problems. Similar conditions in 1939 by Karush.
- Nesterov (1983): accelerated gradient method
- Karmarkar (1984): polynomial time algorithm for LP-problems begins a boom of interior point methods.
- Modern era: nonsmooth analysis, stochastic optimization...



Today we will talk about

- Motivating example
Optimization as a pillar of modern imaging
- Introduction
Overview of optimization
- **Class structure**
Assignments, grades, TAs, etc.

Practical information

Course website:

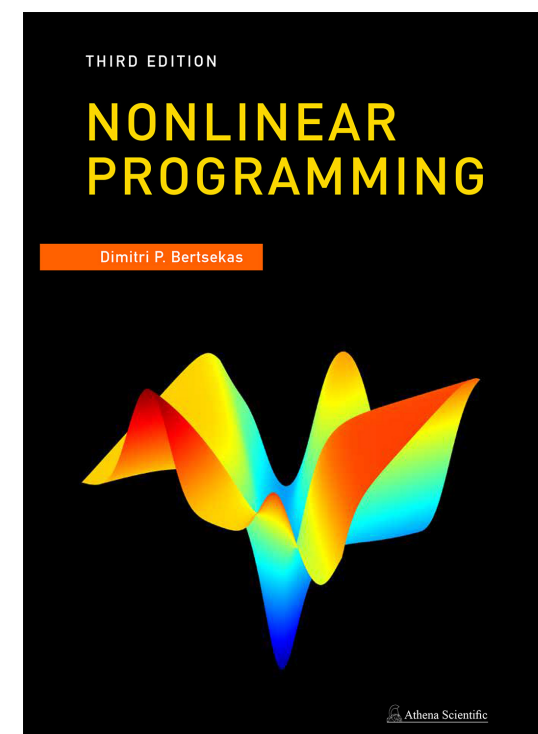
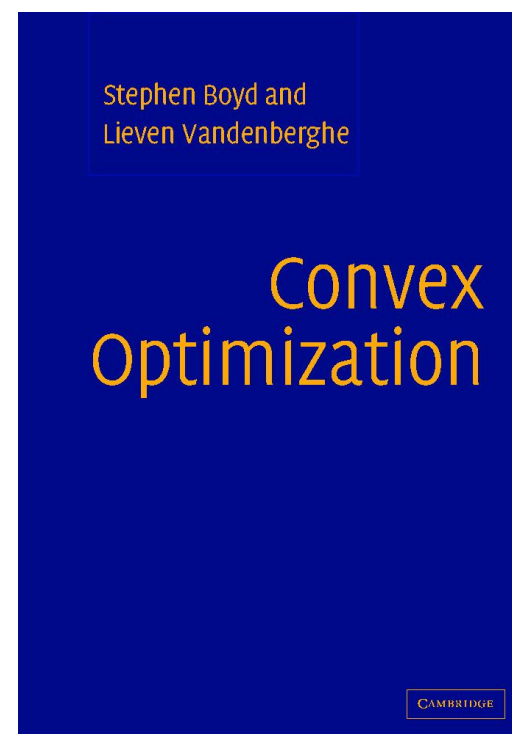
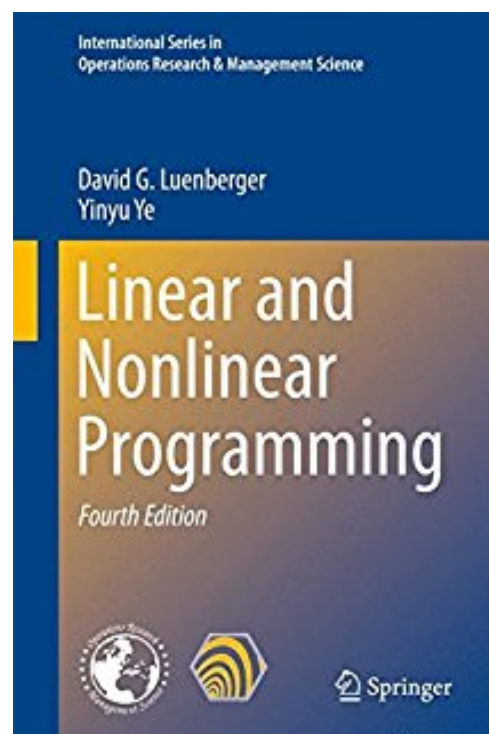
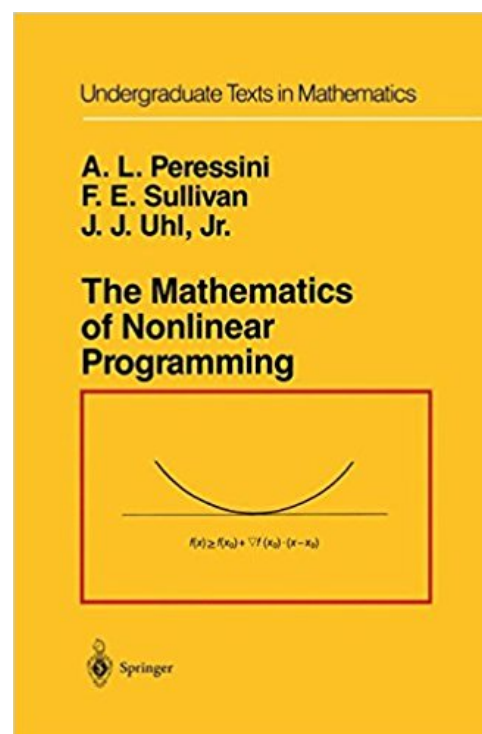
<https://cigroup.wustl.edu/teaching/ese415>

Schedule:

Lectures: Tue and Thu at 1:00-2:30 pm

Recitations: ???

Recommended reading:



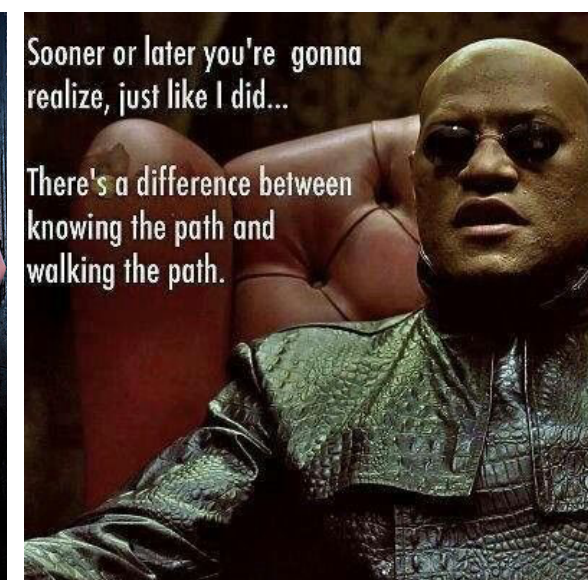
Practical information

By the end of the semester, hopefully, you will be able to:

- recognize and formulate problems as optimization
- characterize optimal solutions
- develop code for optimization algorithms

Topics:

- optimality conditions
- convex sets and functions
- constrained and unconstrained optimization
- optimization algorithms
- analysis of optimization algorithms
- examples and applications



Practical information

Grading policy:

- homework (40%) consists of 6 assignments
- midterm (30%) is on Thursday, 8 March 2017
- final (30%): is on Tuesday, 8 May 2017

Grading convention:

- 93-100 A
- 90-92 A-
- 88-89 B+
- 83-87 B
- 80-82 B-
- 70-79 C
- 60-69 D
- below 60 F

Practical information

Head TAs:

- Hesam Mazidi (hmazidi@wustl.edu)
- Yu Sun (sun.yu@wustl.edu)



TA team:

- Tao Ge (getao@wustl.edu)
- Yueying He (he.yueying@wustl.edu)
- Yunshen Huang (huang.yunshen@wustl.edu)
- Xin Ning (xin.ning@wustl.edu)
- Chang Xue (chang.xue@wustl.edu)
- Boyang Zhou (bzhou24@wustl.edu)
- Yufei Zhou (yufei.zhou@wustl.edu)

Conclusion

Optimization is extensively used in almost all engineering applications

The goal of ESE 415 is to help you understand and apply the basics

Optimization is still an active research area with many open questions



CONTACT INFO

Ulugbek S. Kamilov
Computational Imaging Group (CIG)
Washington University in St. Louis
kamilov@wustl.edu
<http://cigroup.wustl.edu>